

# pyFAI

## API Documentation

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# 1 Package pyFAI

## 1.1 Modules

- **\_geometry** (Section 2, p. 5)
- **azimuthalIntegrator**: This class defines azimuthal integrators (ai here-after). (Section 3, p. 6)
- **bilinear** (Section 4, p. 24)
- **detectors** (Section 5, p. 25)
- **fastcrc**: Simple Cython module for doing CRC32 for checksums, possibly with SSE4 acceleration (Section 6, p. 36)
- **geometry** (Section 7, p. 37)
- **geometryRefinement** (Section 8, p. 50)
- **histogram** (Section 9, p. 55)
- **ocl\_azim**: C++ less implementation of Dimitris' code based on PyOpenCL (Section 10, p. 56)
- **ocl\_azim\_lut** (Section 11, p. 62)
- **opencl** (Section 12, p. 64)
- **peakPicker** (Section 13, p. 68)
- **reconstruct** (Section 14, p. 74)
- **refinement2D** (Section 15, p. 75)
- **relabel** (Section 16, p. 77)
- **spline**: This is piece of software aims to manipulate spline files for geometric corrections of the 2D detectors using cubic-spline (Section 17, p. 78)
- **splitBBox** (Section 18, p. 83)
- **splitBBoxLUT** (Section 19, p. 84)
- **splitPixel** (Section 20, p. 85)
- **utils** (Section 21, p. 86)

## 1.2 Variables

Name	Description
version	<b>Value:</b> '0.8.0'
logger	<b>Value:</b> logging.getLogger("pyFAI.__init__")
__package__	<b>Value:</b> 'pyFAI'

## 2 Module `pyFAI.geometry`

### 2.1 Variables

Name	Description
<code>--package--</code>	<b>Value:</b> <code>'pyFAI'</code>
<code>--test--</code>	<b>Value:</b> <code>{}</code>

### 3 Module `pyFAI.azimuthalIntegrator`

This class defines azimuthal integrators (ai here-after). main methods are:

```
tth,I = ai.xrpd(data,nbPt) q,I,sigma = ai.saxs(data,nbPt)
```

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**Copyright:** European Synchrotron Radiation Facility, Grenoble, France

**License:** GPLv3+

#### 3.1 Variables

Name	Description
<code>__status__</code>	<b>Value:</b> 'beta'
<code>logger</code>	<b>Value:</b> <code>logging.getLogger("pyFAI.azimuthalIntegrator")</code>
<code>ocl</code>	<b>Value:</b> OpenCL devic...
<code>__package__</code>	<b>Value:</b> 'pyFAI'

#### 3.2 Class `AzimuthalIntegrator`



**Known Subclasses:** `pyFAI.geometryRefinement.GeometryRefinement`

This class is an azimuthal integrator based on P. Boesecke's geometry and histogram algorithm by Manolo S. del Rio and V.A Sole

All geometry calculation are done in the Geometry class

### 3.2.1 Methods

```
__init__(self, dist=1, poni1=0, poni2=0, rot1=0, rot2=0, rot3=0, pixel1=None,
pixel2=None, splineFile=None, detector=None)
```

**x.\_\_init\_\_**(...) initializes x; see **x.\_\_class\_\_.\_\_doc\_\_** for signature

#### Parameters

**dist**: distance sample - detector plan (orthogonal distance, not along the beam), in meter.

**poni1**: coordinate of the point of normal incidence along the detector's first dimension, in meter

**poni2**: coordinate of the point of normal incidence along the detector's second dimension, in meter

**rot1**: first rotation from sample ref to detector's ref, in radians

**rot2**: second rotation from sample ref to detector's ref, in radians

**rot3**: third rotation from sample ref to detector's ref, in radians

**pixel1**: pixel size of the fist dimension of the detector, in meter

**pixel2**: pixel size of the second dimension of the detector, in meter

**splineFile**: file containing the geometric distortion of the detector. Overrides the pixel size.

**detector**: name of the detector or Detector instance.

Overrides: **object.\_\_init\_\_**

```
makeMask(self, data, mask=None, dummy=None, delta_dummy=None, mode='normal')
```

Combines various masks...

Normal mode: False for valid pixels, True for bad pixels Numpy mode: True for valid pixels, false for others

#### Parameters

**data**: input array of data

**mask**: input mask (if none, self.mask is used)

**dummy**: value of dead pixels

**delta\_dumy**: precision of dummy pixels

**mode**: can be "normal" or "numpy"

#### Return Value

array of boolean

```
xrpd_numpy(self, data, nbPt, filename=None, correctSolidAngle=True, tthRange=None,
mask=None, dummy=None, delta_dummy=None, polarization_factor=0, dark=None,
flat=None)
```

Calculate the powder diffraction pattern from a set of data, an image. Numpy implementation

#### Parameters

<b>data:</b>	2D array from the CCD camera ( <i>type=ndarray</i> )
<b>nbPt:</b>	number of points in the output pattern ( <i>type=integer</i> )
<b>filename:</b>	file to save data in ( <i>type=string</i> )
<b>correctSolidAngle:</b>	if True, the data are divided by the solid angle of each pixel ( <i>type=boolean</i> )
<b>tthRange:</b>	The lower and upper range of 2theta. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>mask:</b>	array (same size as image) with 0 for masked pixels, and 1 for valid pixels
<b>dummy:</b>	value for dead/masked pixels
<b>delta_dummy:</b>	precision for dummy value
<b>polarization_factor:</b>	polarization factor between -1 and +1. 0 for no correction
<b>dark:</b>	dark noise image
<b>flat:</b>	flat field image

#### Return Value

(2theta, I) in degrees  
(*type=2-tuple of 1D arrays*)

```
xrpd_cython(self, data, nbPt, filename=None, correctSolidAngle=True, tthRange=None,
mask=None, dummy=None, delta_dummy=None, polarization_factor=0, dark=None,
flat=None, pixelSize=None)
```

Calculate the powder diffraction pattern from a set of data, an image.

Old cython implementation, you should not use it.

#### Parameters

<b>data:</b>	2D array from the CCD camera ( <i>type=ndarray</i> )
<b>nbPt:</b>	number of points in the output pattern ( <i>type=integer</i> )
<b>filename:</b>	file to save data in ( <i>type=string</i> )
<b>correctSolidAngle:</b>	if True, the data are divided by the solid angle of each pixel ( <i>type=boolean</i> )
<b>tthRange:</b>	The lower and upper range of the 2theta. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>mask:</b>	array (same size as image) with 1 for masked pixels, and 0 for valid pixels
<b>dummy:</b>	value for dead/masked pixels
<b>delta_dummy:</b>	precision for dummy value
<b>polarization_factor:</b>	polarization factor between -1 and +1. 0 for no correction
<b>dark:</b>	dark noise image
<b>flat:</b>	flat field image
<b>pixelSize:</b>	extension of pixels in 2theta (and radians) ... for pixel splittinh

#### Return Value

(2theta, I) in degrees  
(*type=2-tuple of 1D arrays*)

```
xrpd_splitBBox(self, data, nbPt, filename=None, correctSolidAngle=True,
tthRange=None, chiRange=None, mask=None, dummy=None, delta_dummy=None,
polarization_factor=0, dark=None, flat=None)
```

Calculate the powder diffraction pattern from a set of data, an image. Cython implementation

Add in the cython part a dark and a flat images to be corrected on the fly. This is the default and preferred method.

#### Parameters

<b>data:</b>	2D array from the CCD camera ( <i>type=ndarray</i> )
<b>nbPt:</b>	number of points in the output pattern ( <i>type=integer</i> )
<b>filename:</b>	file to save data in ascii format 2 column ( <i>type=string</i> )
<b>correctSolidAngle:</b>	if True, the data are divided by the solid angle of each pixel ( <i>type=boolean</i> )
<b>tthRange:</b>	The lower and upper range of the 2theta. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>chiRange:</b>	The lower and upper range of the chi angle. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>mask:</b>	array (same size as image) with 0 for masked pixels, and 1 for valid pixels
<b>dummy:</b>	value for dead/masked pixels
<b>delta_dummy:</b>	precision for dummy value
<b>polarization_factor:</b>	polarization factor between -1 and +1. 0 for no correction
<b>dark:</b>	dark noise image
<b>flat:</b>	flat field image

#### Return Value

(2theta, I) in degrees

(*type=2-tuple of 1D arrays*)

```
xrpd_splitPixel(self, data, nbPt, filename=None, correctSolidAngle=True, tthRange=None,
chiRange=None, mask=None, dummy=None, delta_dummy=None, polarization_factor=0,
dark=None, flat=None)
```

Calculate the powder diffraction pattern from a set of data, an image.

Cython implementation

**Parameters**

<b>data:</b>	2D array from the CCD camera ( <i>type=ndarray</i> )
<b>nbPt:</b>	number of points in the output pattern ( <i>type=integer</i> )
<b>filename:</b>	file to save data in ( <i>type=string</i> )
<b>mask:</b>	array (same size as image) with 0 for masked pixels, and 1 for valid pixels
<b>dummy:</b>	value for dead/masked pixels
<b>delta_dummy:</b>	precision for dummy value
<b>polarization_factor:</b>	polarization factor between -1 and +1. 0 for no correction
<b>dark:</b>	dark noise image
<b>flat:</b>	flat field image

**Return Value**

(2theta, I) in degrees  
(*type=2-tuple of 1D arrays*)

```
xrpd(self, data, nbPt, filename=None, correctSolidAngle=True, tthRange=None,
chiRange=None, mask=None, dummy=None, delta_dummy=None, polarization_factor=0,
dark=None, flat=None)
```

Calculate the powder diffraction pattern from a set of data, an image. Cython implementation

Add in the cython part a dark and a flat images to be corrected on the fly. This is the default and preferred method.

#### Parameters

<b>data:</b>	2D array from the CCD camera ( <i>type=ndarray</i> )
<b>nbPt:</b>	number of points in the output pattern ( <i>type=integer</i> )
<b>filename:</b>	file to save data in ascii format 2 column ( <i>type=string</i> )
<b>correctSolidAngle:</b>	if True, the data are divided by the solid angle of each pixel ( <i>type=boolean</i> )
<b>tthRange:</b>	The lower and upper range of the 2theta. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>chiRange:</b>	The lower and upper range of the chi angle. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>mask:</b>	array (same size as image) with 0 for masked pixels, and 1 for valid pixels
<b>dummy:</b>	value for dead/masked pixels
<b>delta_dummy:</b>	precision for dummy value
<b>polarization_factor:</b>	polarization factor between -1 and +1. 0 for no correction
<b>dark:</b>	dark noise image
<b>flat:</b>	flat field image

#### Return Value

(2theta, I) in degrees

(*type=2-tuple of 1D arrays*)

```
xrpd_OpenCL(self, data, nbPt, filename=None, correctSolidAngle=True, tthRange=None,
mask=None, dummy=None, delta_dummy=None, devicetype='gpu', useFp64=True,
platformid=None, deviceid=None, safe=True)
```

Calculate the powder diffraction pattern from a set of data, an image. Cython implementation

#### Parameters

<b>data:</b>	2D array from the CCD camera ( <i>type=ndarray</i> )
<b>nbPt:</b>	number of points in the output pattern ( <i>type=integer</i> )
<b>filename:</b>	file to save data in ascii format 2 column ( <i>type=string</i> )
<b>correctSolidAngle:</b>	if True, the data are divided by the solid angle of each pixel ( <i>type=boolean</i> )
<b>tthRange:</b>	The lower and upper range of the 2theta. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>chiRange:</b>	The lower and upper range of the chi angle. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional, disabled for now</i> )
<b>mask:</b>	array (same size as image) with 0 for masked pixels, and 1 for valid pixels
<b>dummy:</b>	value for dead/masked pixels
<b>delta_dummy:</b>	precision for dummy value
<b>devicetype:</b>	OpenCL specific parameters: "cpu" or "gpu" or "all" or "def"
<b>useFp64:</b>	shall histogram be done in double precision (advised)
<b>platformid:</b>	platform number
<b>deviceid:</b>	device number
<b>safe:</b>	set to false if you think your GPU is already set-up correctly (2theta, mask, solid angle...)

#### Return Value

(2theta, I) in degrees  
(*type=2-tuple of 1D arrays*)

```
xrpd2_numpy(self, data, nbPt2Th, nbPtChi=360, filename=None, correctSolidAngle=True,
tthRange=None, chiRange=None, mask=None, dummy=None, delta_dummy=None)
```

Calculate the 2D powder diffraction pattern (2Theta,Chi) from a set of data, an image

Pure numpy implementation (VERY SLOW !!!)

**Parameters**

**data:** 2D array from the CCD camera  
(*type=ndarray*)

**nbPt2Th:** number of points in the output pattern in the Radial (horizontal) axis (2 theta)

**nbPtChi:** number of points in the output pattern along the Azimuthal (vertical) axis (chi)  
(*type=integer*)

**filename:** file to save data in  
(*type=string*)

**mask:** array (same size as image) with 0 for masked pixels, and 1 for valid pixels

**dummy:** value for dead/masked pixels

**delta\_dummy:** precision for dummy value

**nbPt:** (*type=integer*)

**Return Value**

azimuthally regrouped data, 2theta pos and chipos  
(*type=3-tuple of ndarrays*)

```
xrpd2_histogram(self, data, nbPt2Th, nbPtChi=360, filename=None,  
correctSolidAngle=True, tthRange=None, chiRange=None, mask=None, dummy=None,  
delta_dummy=None)
```

Calculate the 2D powder diffraction pattern (2Theta,Chi) from a set of data, an image

Cython implementation: fast but incaccurate

**Parameters**

**data:** 2D array from the CCD camera  
(*type=ndarray*)

**nbPt2Th:** number of points in the output pattern in the Radial (horizontal)  
axis (2 theta)

**nbPtChi:** number of points in the output pattern along the Azimuthal  
(vertical) axis (chi)  
(*type=integer*)

**filename:** file to save data in  
(*type=string*)

**mask:** array (same siza as image) with 0 for masked pixels, and 1 for  
valid pixels

**dummy:** value for dead/masked pixels

**delta\_dummy:** precision for dummy value

**nbPt:** (*type=integer*)

**Return Value**

azimuthaly regrouped data, 2theta pos and chipos  
(*type=3-tuple of ndarrays*)

```
xrpd2_splitBBox(self, data, nbPt2Th, nbPtChi=360, filename=None,
correctSolidAngle=True, tthRange=None, chiRange=None, mask=None, dummy=None,
delta_dummy=None)
```

Calculate the 2D powder diffraction pattern (2Theta,Chi) from a set of data, an image

Split pixels according to their coordinate and a bounding box

#### Parameters

<b>data:</b>	2D array from the CCD camera ( <i>type=ndarray</i> )
<b>nbPt2Th:</b>	number of points in the output pattern in the Radial (horizontal) axis (2 theta)
<b>nbPtChi:</b>	number of points in the output pattern along the Azimuthal (vertical) axis (chi) ( <i>type=integer</i> )
<b>filename:</b>	file to save data in ( <i>type=string</i> )
<b>correctSolidAngle:</b>	if True, the data are divided by the solid angle of each pixel ( <i>type=boolean</i> )
<b>tthRange:</b>	The lower and upper range of the 2theta. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>chiRange:</b>	The lower and upper range of the azimuthal angle. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>mask:</b>	array (same size as image) with 0 for masked pixels, and 1 for valid pixels
<b>dummy:</b>	value for dead/masked pixels
<b>delta_dummy:</b>	precision for dummy value
<b>nbPt:</b>	( <i>type=integer</i> )

#### Return Value

azimuthally regrouped data, 2theta pos. and chi pos.  
(*type=3-tuple of ndarrays*)

```
xrpd2_splitPixel(self, data, nbPt2Th, nbPtChi=360, filename=None,
correctSolidAngle=True, tthRange=None, chiRange=None, mask=None, dummy=None,
delta_dummy=None, polarization_factor=0, dark=None, flat=None)
```

Calculate the 2D powder diffraction pattern (2Theta,Chi) from a set of data, an image

Split pixels according to their corner positions

#### Parameters

<b>data:</b>	2D array from the CCD camera ( <i>type=ndarray</i> )
<b>nbPt2Th:</b>	number of points in the output pattern in the Radial (horizontal) axis (2 theta)
<b>nbPtChi:</b>	number of points in the output pattern along the Azimuthal (vertical) axis (chi) ( <i>type=integer</i> )
<b>filename:</b>	file to save data in ( <i>type=string</i> )
<b>correctSolidAngle:</b>	if True, the data are divided by the solid angle of each pixel ( <i>type=boolean</i> )
<b>tthRange:</b>	The lower and upper range of the 2theta. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>chiRange:</b>	The lower and upper range of the azimuthal angle. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>mask:</b>	array (same size as image) with 0 for masked pixels, and 1 for valid pixels
<b>dummy:</b>	value for dead/masked pixels
<b>delta_dummy:</b>	precision for dummy value
<b>polarization_factor:</b>	polarization factor between -1 and +1. 0 for no correction
<b>dark:</b>	dark noise image
<b>flat:</b>	flat field image
<b>nbPt:</b>	( <i>type=integer</i> )

#### Return Value

azimuthally regrouped data, 2theta pos. and chi pos.  
(*type=3-tuple of ndarrays*)

```
xrpd2(self, data, nbPt2Th, nbPtChi=360, filename=None, correctSolidAngle=True,
tthRange=None, chiRange=None, mask=None, dummy=None, delta_dummy=None)
```

Calculate the 2D powder diffraction pattern (2Theta,Chi) from a set of data, an image

Split pixels according to their coordinate and a bounding box

#### Parameters

<b>data:</b>	2D array from the CCD camera ( <i>type=ndarray</i> )
<b>nbPt2Th:</b>	number of points in the output pattern in the Radial (horizontal) axis (2 theta)
<b>nbPtChi:</b>	number of points in the output pattern along the Azimuthal (vertical) axis (chi) ( <i>type=integer</i> )
<b>filename:</b>	file to save data in ( <i>type=string</i> )
<b>correctSolidAngle:</b>	if True, the data are divided by the solid angle of each pixel ( <i>type=boolean</i> )
<b>tthRange:</b>	The lower and upper range of the 2theta. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>chiRange:</b>	The lower and upper range of the azimuthal angle. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>mask:</b>	array (same size as image) with 0 for masked pixels, and 1 for valid pixels
<b>dummy:</b>	value for dead/masked pixels
<b>delta_dummy:</b>	precision for dummy value
<b>nbPt:</b>	( <i>type=integer</i> )

#### Return Value

azimuthally regrouped data, 2theta pos. and chi pos.  
(*type=3-tuple of ndarrays*)

```
save2D(self, filename, I, dim1, dim2, dim1_unit='2th')
```

```
saxs(self, data, nbPt, filename=None, correctSolidAngle=True, variance=None,
error_model=None, qRange=None, chiRange=None, mask=None, dummy=None,
delta_dummy=None, polarization_factor=0, dark=None, flat=None, method='bbox')
```

Calculate the azimuthal integrated Saxes curve

Multi algorithm implementation (tries to be bullet proof)

#### Parameters

<b>data:</b>	2D array from the CCD camera ( <i>type=ndarray</i> )
<b>nbPt:</b>	number of points in the output pattern ( <i>type=integer</i> )
<b>filename:</b>	file to save data to ( <i>type=string</i> )
<b>correctSolidAngle:</b>	if True, the data are divided by the solid angle of each pixel ( <i>type=boolean</i> )
<b>variance:</b>	array containing the variance of the data, if you know it ( <i>type=ndarray</i> )
<b>error_model:</b>	When the variance is unknown, an error model can be given: "poisson" (variance = I), "azimuthal" (variance = $(I - \langle I \rangle)^2$ ) ( <i>type=string</i> )
<b>qRange:</b>	The lower and upper range of the scatter vector q. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>chiRange:</b>	The lower and upper range of the chi angle. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>mask:</b>	array (same size as image) with 1 for masked pixels, and 0 for valid pixels
<b>dummy:</b>	value for dead/masked pixels
<b>delta_dummy:</b>	precision for dummy value
<b>polarization_factor:</b>	polarization factor between -1 and +1. 0 for no correction
<b>dark:</b>	dark noise image
<b>flat:</b>	flat field image
<b>method:</b>	can be "numpy", "cython", "BBox" or "splitpixel"

#### Return Value

azimuthally regrouped data, 2theta pos. and chi pos.  
(*type=3-tuple of ndarrays*)

**makeHeaders**(*self*, *hdr*='#')

---

**Return Value**

a string to be used for headers

**get\_darkcurrent**(*self*)

**get\_flatfield**(*self*)

**get\_mask**(*self*)

**get\_maskfile**(*self*)

**reset**(*self*)

---

Reset azimuthal integrator in addition to other arrays.

Overrides: `pyFAI.geometry.Geometry.reset`

**save1D**(*self*, *filename*, *dim1*, *I*, *error*=None, *dim1\_unit*='2th\_deg')

**set\_darkcurrent**(*self*, *dark*)

**set\_flatfield**(*self*, *flat*)

**set\_mask**(*self*, *mask*)

**set\_maskfile**(*self*, *maskfile*)

**setup\_LUT**(*self*, *shape*, *nbPt*, *mask*=None, *tthRange*=None, *chiRange*=None, *mask\_checksum*=None)

```
xrpd_LUT(self, data, nbPt, filename=None, correctSolidAngle=True, tthRange=None,
chiRange=None, mask=None, dummy=None, delta_dummy=None, safe=True)
```

Calculate the powder diffraction pattern from a set of data, an image. Cython implementation using a Look-Up Table.

#### Parameters

<b>data:</b>	2D array from the CCD camera ( <i>type=ndarray</i> )
<b>nbPt:</b>	number of points in the output pattern ( <i>type=integer</i> )
<b>filename:</b>	file to save data in ascii format 2 column ( <i>type=string</i> )
<b>correctSolidAngle:</b>	if True, the data are divided by the solid angle of each pixel ( <i>type=boolean</i> )
<b>tthRange:</b>	The lower and upper range of the 2theta. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>chiRange:</b>	The lower and upper range of the chi angle. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional, disabled for now</i> )
<b>mask:</b>	array (same size as image) with 0 for masked pixels, and 1 for valid pixels
<b>dummy:</b>	value for dead/masked pixels
<b>delta_dummy:</b>	precision for dummy value LUT specific parameters:
<b>safe:</b>	set to false if you think your GPU is already set-up correctly (2theta, mask, solid angle...)

#### Return Value

(2theta, I) in degrees  
(*type=2-tuple of 1D arrays*)

```
xrpd_LUT_OCL(self, data, nbPt, filename=None, correctSolidAngle=True,
tthRange=None, chiRange=None, mask=None, dummy=None, delta_dummy=None,
safe=True, devicetype='all', platformid=None, deviceid=None)
```

Calculate the powder diffraction pattern from a set of data, an image. Cython implementation using a Look-Up Table.

**Parameters**

<b>data:</b>	2D array from the CCD camera ( <i>type=ndarray</i> )
<b>nbPt:</b>	number of points in the output pattern ( <i>type=integer</i> )
<b>filename:</b>	file to save data in ascii format 2 column ( <i>type=string</i> )
<b>correctSolidAngle:</b>	if True, the data are divided by the solid angle of each pixel ( <i>type=boolean</i> )
<b>tthRange:</b>	The lower and upper range of the 2theta. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional</i> )
<b>chiRange:</b>	The lower and upper range of the chi angle. If not provided, range is simply (data.min(), data.max()). Values outside the range are ignored. ( <i>type=(float, float), optional, disabled for now</i> )
<b>mask:</b>	array (same size as image) with 0 for masked pixels, and 1 for valid pixels
<b>dummy:</b>	value for dead/masked pixels
<b>delta_dummy:</b>	precision for dummy value LUT specific parameters:
<b>safe:</b>	set to false if you think your GPU is already set-up correctly (2theta, mask, solid angle...) OpenCL specific parameters:
<b>devicetype:</b>	can be "all", "cpu" or "gpu"

**Return Value**

(2theta, I) in degrees  
(*type=2-tuple of 1D arrays*)

**Inherited from *pyFAI.geometry.Geometry*(Section 7.2)**

`__repr__()`, `calcfrom1d()`, `chi()`, `chiArray()`, `chi_corner()`, `cornerArray()`, `cornerQArray()`, `del_chia()`, `del_dssa()`, `del_qa()`, `del_ttha()`, `delta2Theta()`, `deltaChi()`, `deltaQ()`, `diffSolidAngle()`, `getFit2D()`, `getPyFAI()`, `get_chia()`, `get_correct_solid_angle_for_spline()`, `get_dist()`, `get_dssa()`, `get_pixel1()`, `get_pixel2()`, `get_poni1()`, `get_poni2()`, `get_qa()`, `get_rot1()`, `get_rot2()`, `get_rot3()`, `get_spline()`, `get_splineFile()`, `get_ttha()`, `get_wavelength()`, `load()`, `oversampleArray()`, `polarization()`, `qArray()`, `qCornerFunc()`, `qFunction()`,

read(), save(), setChiDiscAtPi(), setChiDiscAtZero(), setFit2D(), setOversampling(), setPyFAI(), set\_chia(), set\_correct\_solid\_angle\_for\_spline(), set\_dist(), set\_dssa(), set\_pixel1(), set\_pixel2(), set\_poni1(), set\_poni2(), set\_qa(), set\_rot1(), set\_rot2(), set\_rot3(), set\_spline(), set\_splineFile(), set\_ttha(), set\_wavelength(), sload(), solidAngleArray(), tth(), tth\_corner(), twoThetaArray(), write()

### ***Inherited from object***

\_\_delattr\_\_(), \_\_format\_\_(), \_\_getattr\_\_(), \_\_hash\_\_(), \_\_new\_\_(), \_\_reduce\_\_(), \_\_reduce\_ex\_\_(), \_\_setattr\_\_(), \_\_sizeof\_\_(), \_\_str\_\_(), \_\_subclasshook\_\_()

### **3.2.2 Properties**

Name	Description
darkcurrent	
flatfield	
mask	
maskfile	
<i>Inherited from pyFAI.geometry.Geometry (Section 7.2)</i>	
chia, correct_SA_spline, dist, dssa, pixel1, pixel2, poni1, poni2, qa, rot1, rot2, rot3, spline, splineFile, ttha, wavelength	
<i>Inherited from object</i>	
__class__	

## 4 Module `pyFAI.bilinear`

**Date:** 27/10/2012

**Author:** Jerome Kieffer

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**Copyright:** 2011-2012, ESRF

**License:** GPLv3

### 4.1 Variables

Name	Description
<code>--package--</code>	<b>Value:</b> 'pyFAI'
<code>--test--</code>	<b>Value:</b> {}

## 5 Module *pyFAI.detectors*

**Date:** 12/04/2012

**Author:** Jérôme Kieffer

**Contact:** Jerome.Kieffer@ESRF.eu

**Copyright:** European Synchrotron Radiation Facility, Grenoble, France

**License:** GPLv3+

### 5.1 Functions

<b>detector_factory</b> ( <i>name</i> )
A kind of factory...
<b>Parameters</b>
<i>name</i> : name of a detector
<b>Return Value</b>
an instance of the right detector

### 5.2 Variables

Name	Description
<code>__status__</code>	<b>Value:</b> 'beta'
<code>logger</code>	<b>Value:</b> <code>logging.getLogger("pyFAI.detectors")</code>
<code>ALL_DETECTORS</code>	<b>Value:</b> {'condor': <class 'pyFAI.detectors.Fairchild'>, 'fairchil...'
<code>__package__</code>	<b>Value:</b> 'pyFAI'

### 5.3 Class Detector

object —  
    **pyFAI.detectors.Detector**

**Known Subclasses:** *pyFAI.detectors.FReLoN*, *pyFAI.detectors.Fairchild*, *pyFAI.detectors.Pilatus*, *pyFAI.detectors.Xpad.flat*

Generic class representing a 2D detector

### 5.3.1 Methods

```
__init__(self, pixel1=None, pixel2=None, splineFile=None)
```

*x*.**\_\_init\_\_**(...) initializes *x*; see *x*.**\_\_class\_\_**.**\_\_doc\_\_** for signature

Overrides: object.**\_\_init\_\_** **exitit**(inherited documentation)

```
__repr__(self)
```

**repr**(*x*)

Overrides: object.**\_\_repr\_\_** **exitit**(inherited documentation)

```
get_splineFile(self)
```

```
set_splineFile(self, splineFile)
```

```
get_binning(self)
```

```
set_binning(self, bin_size=(1, 1))
```

```
getPyFAI(self)
```

```
getFit2D(self)
```

```
setPyFAI(self, **kwarg)
```

```
setFit2D(self)
```

**calc\_cartesian\_positions**(*self*, *d1*=None, *d2*=None)

Calculate the position of each pixel center in cartesian coordinate and in meter of a couple of coordinates. The half pixel offset is taken into account here !!!

**Parameters**

*d1*: ndarray of dimension 1 or 2 containing the Y pixel positions

*d2*: ndarray of dimension 1 or 2 containing the X pixel positions

**Return Value**

2-arrays of same shape as *d1* & *d2* with the position in meter

*d1* and *d2* must have the same shape, returned array will have the same shape.

**calc\_mask**(*self*)

Detectors with gaps should overwrite this method with something actually calculating the mask!

**get\_mask**(*self*)

**set\_mask**(*self*, *mask*)

**set\_maskfile**(*self*, *maskfile*)

**get\_maskfile**(*self*)

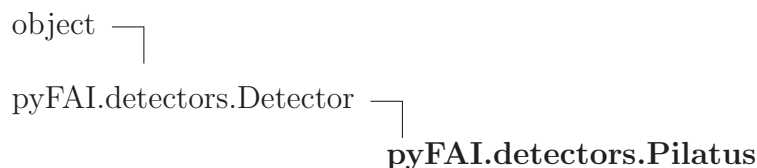
**Inherited from object**

`__delattr__()`, `__format__()`, `__getattr__()`, `__hash__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`, `__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

### 5.3.2 Properties

Name	Description
splineFile	
binning	
mask	
maskfile	
<i>Inherited from object</i>	
<code>__class__</code>	

## 5.4 Class Pilatus



**Known Subclasses:** pyFAI.detectors.Pilatus1M, pyFAI.detectors.Pilatus2M, pyFAI.detectors.Pilatus6M

Pilatus detector: generic description

### 5.4.1 Methods

```
__init__(self, pixel1=0.000172, pixel2=0.000172)
x.__init__(...) initializes x; see x.__class__.__doc__ for signature
Overrides: object.__init__ extit(inherited documentation)
```

```
__repr__(self)
repr(x)
Overrides: object.__repr__ extit(inherited documentation)
```

```
calc_mask(self)
Returns a generic mask for Pilatus detectors...
Overrides: pyFAI.detectors.Detector.calc_mask
```

**Inherited from pyFAI.detectors.Detector(Section 5.3)**

```
calc_cartesian_positions(), getFit2D(), getPyFAI(), get_binning(), get_mask(), get_maskfile(),
get_splineFile(), setFit2D(), setPyFAI(), set_binning(), set_mask(), set_maskfile(),
set_splineFile()
```

**Inherited from object**

```
__delattr__(), __format__(), __getattr__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(),
__setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 5.4.2 Properties

Name	Description
<i>Inherited from pyFAI.detectors.Detector (Section 5.3)</i>	

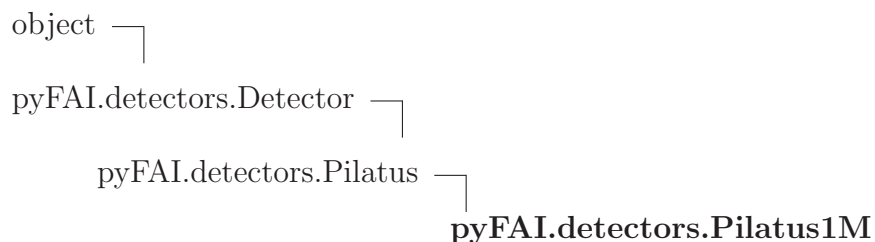
*continued on next page*

Name	Description
binning, mask, maskfile, splineFile	
<i>Inherited from object</i>	
__class__	

### 5.4.3 Class Variables

Name	Description
MODULE_SIZE	<b>Value:</b> (195, 487)
MODULE_GAP	<b>Value:</b> (17, 7)

## 5.5 Class *Pilatus1M*



Pilatus 1M detector

### 5.5.1 Methods

```

__init__(self, pixel1=0.000172, pixel2=0.000172)

x.__init__(...) initializes x; see x.__class__.__doc__ for signature
Overrides: object.__init__ extit(inherited documentation)

```

***Inherited from pyFAI.detectors.Pilatus(Section 5.4)***

`__repr__()`, `calc_mask()`

***Inherited from pyFAI.detectors.Detector(Section 5.3)***

`calc_cartesian_positions()`, `getFit2D()`, `getPyFAI()`, `get_binning()`, `get_mask()`, `get_maskfile()`, `get_splineFile()`, `setFit2D()`, `setPyFAI()`, `set_binning()`, `set_mask()`, `set_maskfile()`, `set_splineFile()`

***Inherited from object***

`__delattr__()`, `__format__()`, `__getattr__()`, `__hash__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`,

`__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

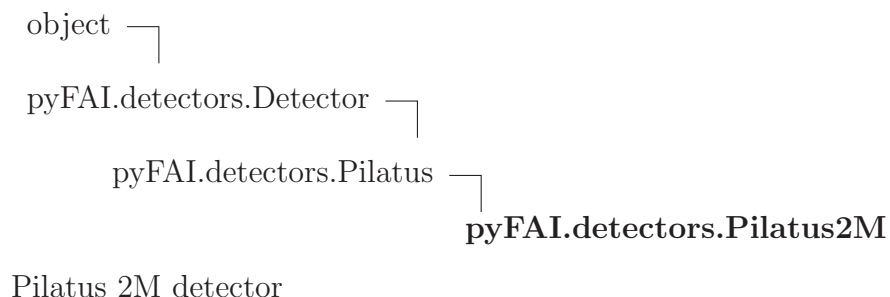
### 5.5.2 Properties

Name	Description
<i>Inherited from <code>pyFAI.detectors.Detector</code> (Section 5.3)</i>	<code>binning</code> , <code>mask</code> , <code>maskfile</code> , <code>splineFile</code>
<i>Inherited from object</i>	<code>__class__</code>

### 5.5.3 Class Variables

Name	Description
<i>Inherited from <code>pyFAI.detectors.Pilatus</code> (Section 5.4)</i>	<code>MODULE_GAP</code> , <code>MODULE_SIZE</code>

## 5.6 Class *Pilatus2M*



### 5.6.1 Methods

<code>__init__(self, pixel1=0.000172, pixel2=0.000172)</code>
<code>x.__init__(...)</code> initializes <code>x</code> ; see <code>x.__class__.__doc__</code> for signature
Overrides: <code>object.__init__</code> <code>extit</code> (inherited documentation)

*Inherited from `pyFAI.detectors.Pilatus` (Section 5.4)*

`__repr__()`, `calc_mask()`

*Inherited from `pyFAI.detectors.Detector` (Section 5.3)*

`calc_cartesian_positions()`, `getFit2D()`, `getPyFAI()`, `get_binning()`, `get_mask()`, `get_maskfile()`,

`get_splineFile()`, `setFit2D()`, `setPyFAI()`, `set_binning()`, `set_mask()`, `set_maskfile()`,  
`set_splineFile()`

### *Inherited from object*

`__delattr__()`, `__format__()`, `__getattr__()`, `__hash__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`,  
`__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

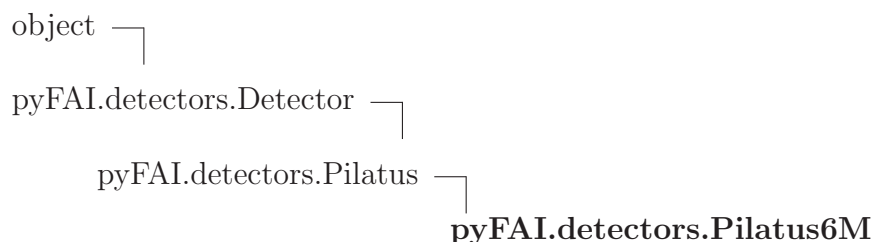
#### 5.6.2 Properties

Name	Description
<i>Inherited from pyFAI.detectors.Detector (Section 5.3)</i>	<code>binning</code> , <code>mask</code> , <code>maskfile</code> , <code>splineFile</code>
<i>Inherited from object</i>	<code>__class__</code>

#### 5.6.3 Class Variables

Name	Description
<i>Inherited from pyFAI.detectors.Pilatus (Section 5.4)</i>	<code>MODULE_GAP</code> , <code>MODULE_SIZE</code>

### 5.7 Class *Pilatus6M*



Pilatus 6M detector

#### 5.7.1 Methods

`__init__(self, pixel1=0.000172, pixel2=0.000172)`  
`x.__init__(...)` initializes `x`; see `x.__class__.__doc__` for signature  
 Overrides: `object.__init__` `exitit`(inherited documentation)

*Inherited from pyFAI.detectors.Pilatus(Section 5.4)*

`__repr__()`, `calc_mask()`

***Inherited from pyFAI.detectors.Detector (Section 5.3)***

`calc_cartesian_positions()`, `getFit2D()`, `getPyFAI()`, `get_binning()`, `get_mask()`, `get_maskfile()`,  
`get_splineFile()`, `setFit2D()`, `setPyFAI()`, `set_binning()`, `set_mask()`, `set_maskfile()`,  
`set_splineFile()`

***Inherited from object***

`__delattr__()`, `__format__()`, `__getattr__()`, `__hash__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`,  
`__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

### 5.7.2 Properties

Name	Description
<i>Inherited from pyFAI.detectors.Detector (Section 5.3)</i>	
binning, mask, maskfile, splineFile	
<i>Inherited from object</i>	
__class__	

### 5.7.3 Class Variables

Name	Description
<i>Inherited from pyFAI.detectors.Pilatus (Section 5.4)</i>	
MODULE_GAP, MODULE_SIZE	

## 5.8 Class Fairchild

```

object └─
    pyFAI.detectors.Detector └─
                                pyFAI.detectors.Fairchild

```

Fairchild Condor 486:90 detector

### 5.8.1 Methods

**\_\_init\_\_**(*self*, *pixel1*=1.5e-05, *pixel2*=1.5e-05)

*x*.\_\_init\_\_(...) initializes *x*; see *x*.\_\_class\_\_.\_\_doc\_\_ for signature

Overrides: object.\_\_init\_\_ extit(inherited documentation)

#### *Inherited from pyFAI.detectors.Detector (Section 5.3)*

\_\_repr\_\_(), calc\_cartesian\_positions(), calc\_mask(), getFit2D(), getPyFAI(), get\_binning(),  
get\_mask(), get\_maskfile(), get\_splineFile(), setFit2D(), setPyFAI(), set\_binning(),  
set\_mask(), set\_maskfile(), set\_splineFile()

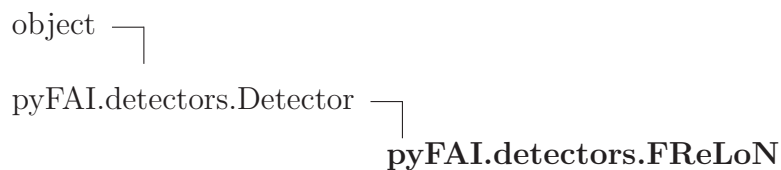
#### *Inherited from object*

\_\_delattr\_\_(), \_\_format\_\_(), \_\_getattr\_\_(), \_\_hash\_\_(), \_\_new\_\_(), \_\_reduce\_\_(), \_\_reduce\_ex\_\_(),  
\_\_setattr\_\_(), \_\_sizeof\_\_(), \_\_str\_\_(), \_\_subclasshook\_\_()

### 5.8.2 Properties

Name	Description
<i>Inherited from pyFAI.detectors.Detector (Section 5.3)</i>	
binning, mask, maskfile, splineFile	
<i>Inherited from object</i>	
__class__	

## 5.9 Class FReLoN



FReLoN detector (spline mandatory to correct for geometric distortion)

### 5.9.1 Methods

**\_\_init\_\_**(*self*, *splineFile*)

*x*.\_\_init\_\_(...) initializes *x*; see *x*.\_\_class\_\_.\_\_doc\_\_ for signature

Overrides: object.\_\_init\_\_ extit(inherited documentation)

***Inherited from pyFAI.detectors.Detector(Section 5.3)***

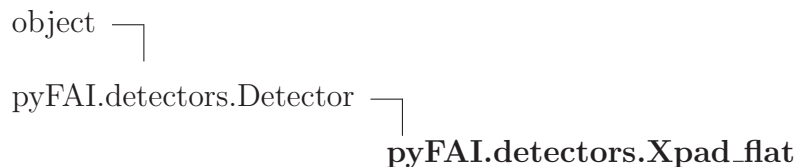
`__repr__()`, `calc_cartesian_positions()`, `calc_mask()`, `getFit2D()`, `getPyFAI()`, `get_binning()`,  
`get_mask()`, `get_maskfile()`, `get_splineFile()`, `setFit2D()`, `setPyFAI()`, `set_binning()`,  
`set_mask()`, `set_maskfile()`, `set_splineFile()`

***Inherited from object***

`__delattr__()`, `__format__()`, `__getattr__()`, `__hash__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`,  
`__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

**5.9.2 Properties**

Name	Description
<i>Inherited from pyFAI.detectors.Detector (Section 5.3)</i>	
binning, mask, maskfile, splineFile	
<i>Inherited from object</i>	
__class__	

**5.10 Class Xpad\_flat**

Xpad detector: generic description for image with

**5.10.1 Methods**

<b><code>__init__(self, pixel1=0.00013, pixel2=0.00013)</code></b>  <code>x.__init__(...)</code> initializes x; see <code>x.__class__.__doc__</code> for signature Overrides: <code>object.__init__</code> extit(inherited documentation)
<b><code>__repr__(self)</code></b>  <code>repr(x)</code> Overrides: <code>object.__repr__</code> extit(inherited documentation)

**calc\_mask(*self*)**

Returns a generic mask for Xpad detectors... discards the first line and raw form all modules: those are 2.5x bigger and often mis - behaving

Overrides: pyFAI.detectors.Detector.calc\_mask

**calc\_cartesian\_positions(*self*, *d1*=None, *d2*=None)**

Calculate the position of each pixel center in cartesian coordinate and in meter of a couple of coordinates. The half pixel offset is taken into account here !!!

**Parameters**

*d1*: ndarray of dimension 1 or 2 containing the Y pixel positions

*d2*: ndarray of dimension 1or 2 containing the X pixel positions

**Return Value**

2-arrays of same shape as *d1* & *d2* with the position in meter

*d1* and *d2* must have the same shape, returned array will have the same shape.

Overrides: pyFAI.detectors.Detector.calc\_cartesian\_positions

***Inherited from pyFAI.detectors.Detector(Section 5.3)***

getFit2D(), getPyFAI(), get\_binning(), get\_mask(), get\_maskfile(), get\_splineFile(), setFit2D(), setPyFAI(), set\_binning(), set\_mask(), set\_maskfile(), set\_splineFile()

***Inherited from object***

\_\_delattr\_\_(), \_\_format\_\_(), \_\_getattr\_\_(), \_\_hash\_\_(), \_\_new\_\_(), \_\_reduce\_\_(), \_\_reduce\_ex\_\_(), \_\_setattr\_\_(), \_\_sizeof\_\_(), \_\_str\_\_(), \_\_subclasshook\_\_()

**5.10.2 Properties**

Name	Description
<i>Inherited from pyFAI.detectors.Detector (Section 5.3)</i>	
binning, mask, maskfile, splineFile	
<i>Inherited from object</i>	
__class__	

**5.10.3 Class Variables**

Name	Description
MODULE_SIZE	<b>Value:</b> (120, 80)
MODULE_GAP	<b>Value:</b> (30.4615384615, 3)

## 6 Module **pyFAI.fastcrc**

Simple Cython module for doing CRC32 for checksums, possibly with SSE4 acceleration

**Date:** 19-11-2012

**Author:** Jerome Kieffer

**Contact:** Jerome.kieffer@esrf.fr

**License:** GPL v3+

### 6.1 Variables

Name	Description
<code>--package--</code>	<b>Value:</b> 'pyFAI'
<code>--test--</code>	<b>Value:</b> {}

## 7 Module *pyFAI.geometry*

**Date:** 09/06/2012

**Author:** Jerome Kieffer

**Contact:** Jerome.Kieffer@ESRF.eu

**Copyright:** European Synchrotron Radiation Facility, Grenoble, France

**License:** GPLv3+

### 7.1 Variables

Name	Description
<code>--status--</code>	<b>Value:</b> 'beta'
<code>logger</code>	<b>Value:</b> <code>logging.getLogger("pyFAI.geometry")</code>
<code>--package--</code>	<b>Value:</b> 'pyFAI'

### 7.2 Class Geometry

object └─ `pyFAI.geometry.Geometry`

**Known Subclasses:** `pyFAI.azimuthalIntegrator.AzimuthalIntegrator`

This class is an azimuthal integrator based on P. Boesecke's geometry and histogram algorithm by Manolo S. del Rio and V.A Sole

Detector is assumed to be corrected from "raster orientation" effect.

It is not addressed here but rather in the Detector object or at read time.

Considering there is no tilt:

Detector fast dimension (`dim2`) is supposed to be horizontal (dimension X of the image)

Detector slow dimension (`dim1`) is supposed to be vertical, upwards (dimension Y of the image)

The third dimension is chose such as the referential is orthonormal, so `dim3` is along image Z

Demonstration of the equation done using Mathematica.

=====

Axis 1 is along first dimension of detector (when not tilted), this is the slow dimension

```

x1={1,0,0}
Axis 2 is along second dimension of detector (when not tilted), this is the fast dimension
x2={0,1,0}
Axis 3 is along the incident X-Ray beam
x3={0,0,1}
We define the 3 rotation around axis 1, 2 and 3:
rotM1 = RotationMatrix[rot1,x1] = {{1,0,0},{0,cos[rot1],-sin[rot1]},{0,sin[rot1],cos[rot1]}}
rotM2 = RotationMatrix[rot2,x2] = {{cos[rot2],0,sin[rot2]},{0,1,0},{-sin[rot2],0,cos[rot2]}}
rotM3 = RotationMatrix[rot3,x3] = {{cos[rot3],-sin[rot3],0},{sin[rot3],cos[rot3],0},{0,0,1}}

Rotations of the detector are applied first Rot around axis 1, then axis 2 and finally axis 3:
R = rotM3.rotM2.rotM1
R = {{cos[rot2] cos[rot3],cos[rot3] sin[rot1] sin[rot2]-cos[rot1] sin[rot3],cos[rot1] cos[rot3] sin[rot2]+sin[rot1] sin[rot3],-cos[rot2] sin[rot3],cos[rot1] cos[rot3]+sin[rot1] sin[rot2] sin[rot3],-cos[rot1] sin[rot2] sin[rot3],-sin[rot2],cos[rot2] sin[rot1],cos[rot1] cos[rot2]}}
In Python notation:
PForm[R.x1] = [cos(rot2)*cos(rot3),cos(rot2)*sin(rot3),-sin(rot2)]
PForm[R.x2] = [cos(rot3)*sin(rot1)*sin(rot2) - cos(rot1)*sin(rot3),cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3),-cos(rot3)*sin(rot1)]
PForm[R.x3] = [cos(rot1)*cos(rot3)*sin(rot2) + sin(rot1)*sin(rot3),-(cos(rot3)*sin(rot1) + cos(rot1)*sin(rot2)*sin(rot3)),L*cos(rot1)*cos(rot2)]

* Coordinates of the Point of Normal Incidence:
PONI = R.{0,0,L}
PForm[PONI] = [L*(cos(rot1)*cos(rot3)*sin(rot2) + sin(rot1)*sin(rot3)),
               L*(-(cos(rot3)*sin(rot1)) + cos(rot1)*sin(rot2)*sin(rot3)),L*cos(rot1)*cos(rot2)]

* Any pixel on detector plan at coordinate (d1, d2) in meters. Detector is at z=L
P={d1,d2,L}
PForm[R.P] = [t1, t2, t3] =
              [d1*cos(rot2)*cos(rot3) + d2*(cos(rot3)*sin(rot1)*sin(rot2) - cos(rot1)*sin(rot3)),
               d1*cos(rot2)*sin(rot3) + d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3)),
               d2*cos(rot2)*sin(rot1) - d1*sin(rot2) + L*cos(rot1)*cos(rot2)]

* Distance sample (origin) to detector point (d1,d2)
FForm[Norm[R.P]] = sqrt(pow(Abs(L*cos(rot1)*cos(rot2) + d2*cos(rot2)*sin(rot1) - d1*sin(rot2)),2) +
                        pow(Abs(d1*cos(rot2)*cos(rot3) + d2*(cos(rot3)*sin(rot1)*sin(rot2) - cos(rot1)*sin(rot3)),2) +
                        L*(cos(rot1)*cos(rot3)*sin(rot2) + sin(rot1)*sin(rot3))),2) +
                    pow(Abs(d1*cos(rot2)*sin(rot3) + L*(-(cos(rot3)*sin(rot1)) + cos(rot1)*sin(rot2)*sin(rot3))),2))

* cos(2theta) is defined as (R.P component along x3) over the distance from origin to detector point
tth = ArcCos [- (R.P).x3/Norm[R.P]]
FForm[tth] = Arccos((-L*cos(rot1)*cos(rot2)) - d2*cos(rot2)*sin(rot1) + d1*sin(rot2))/Norm[R.P]

```

```

sqrt(pow(Abs(L*cos(rot1)*cos(rot2) + d2*cos(rot2)*sin(rot1) - d1*sin
pow(Abs(d1*cos(rot2)*cos(rot3) + d2*(cos(rot3)*sin(rot1)*sin(rot2)
L*(cos(rot1)*cos(rot3)*sin(rot2) + sin(rot1)*sin(rot3))),2) +
pow(Abs(d1*cos(rot2)*sin(rot3) + L*(-(cos(rot3)*sin(rot1)) + cos(r
d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3))),2)))

```

```

* tan(2theta) is defined as sqrt(t1**2 + t2**2) / t3
tth = ArcTan2 [sqrt(t1**2 + t2**2) , t3 ]

```

Getting 2theta from it's tangeant seems both more precise (around beam stop very far from) Currently there is a swich in the method to follow one path or the other.

```

* Tangeant of angle chi is defined as (R.P component along x1) over (R.P component along
chi = ArcTan[((R.P).x1) / ((R.P).x2)]
FForm[chi] = ArcTan2(d1*cos(rot2)*cos(rot3) + d2*(cos(rot3)*sin(rot1)*sin(rot2) - cos(r
L*(cos(rot1)*cos(rot3)*sin(rot2) + sin(rot1)*sin(rot3))),
d1*cos(rot2)*sin(rot3) + L*(-(cos(rot3)*sin(rot1)) + cos(rot1)*sin
d2*(cos(rot1)*cos(rot3) + sin(rot1)*sin(rot2)*sin(rot3)))

```

## 7.2.1 Methods

```
__init__(self, dist=1, poni1=0, poni2=0, rot1=0, rot2=0, rot3=0,
pixel1=None, pixel2=None, splineFile=None, detector=None)
```

`x.__init__(...)` initializes `x`; see `x.__class__.__doc__` for signature

**Parameters**

**dist:** distance sample - detector plan (orthogonal distance, not along the beam), in meter.

**poni1:** coordinate of the point of normal incidence along the detector's first dimension, in meter

**poni2:** coordinate of the point of normal incidence along the detector's second dimension, in meter

**rot1:** first rotation from sample ref to detector's ref, in radians

**rot2:** second rotation from sample ref to detector's ref, in radians

**rot3:** third rotation from sample ref to detector's ref, in radians

**pixel1:** pixel size of the first dimension of the detector, in meter

**pixel2:** pixel size of the second dimension of the detector, in meter

**splineFile:** file containing the geometric distortion of the detector. Overrides the pixel size.

Overrides: `object.__init__`

```
__repr__(self)
```

`repr(x)`

Overrides: `object.__repr__` `exitit`(inherited documentation)

---

**tth**(*self*, *d1*, *d2*, *param*=None, *path*='cython')

---

Calculates the 2theta value for the center of a given pixel (or set of pixels)

**Parameters**

**d1:** position(s) in pixel in first dimension (c order)

*(type=scalar or array of scalar)*

**d2:** position(s) in pixel in second dimension (c order)

*(type=scalar or array of scalar)*

**path:** can be "cos", "tan" or "cython" @return 2theta in radians

**Return Value**

float or array of floats.

---

**qFunction**(*self*, *d1*, *d2*, *param*=None, *path*='cython')

---

Calculates the q value for the center of a given pixel (or set of pixels) in nm<sup>-1</sup>

$$q = 4\pi/\lambda \sin(2\theta / 2)$$

**Parameters**

**d1:** position(s) in pixel in first dimension (c order)

*(type=scalar or array of scalar)*

**d2:** position(s) in pixel in second dimension (c order)

*(type=scalar or array of scalar @return q in in nm<sup>-1</sup>)*

**Return Value**

float or array of floats.

---

**qArray**(*self*, *shape*)

---

Generate an array of the given shape with q(i,j) for all elements.

---

**qCornerFunc**(*self*, *d1*, *d2*)

---

calculate the q\_vector for any pixel corner

**tth\_corner**(*self*, *d1*, *d2*)

Calculates the 2theta value for the corner of a given pixel (or set of pixels)

**Parameters**

**d1:** position(s) in pixel in first dimension (c order)

(*type=scalar or array of scalar*)

**d2:** position(s) in pixel in second dimension (c order)

(*type=scalar or array of scalar @return 2theta in radians*)

**Return Value**

float or array of floats.

**twoThetaArray**(*self*, *shape*)

Generate an array of the given shape with two-theta(i,j) for all elements.

**chi**(*self*, *d1*, *d2*, *path*='cython')

Calculate the chi (azimuthal angle) for the centre of a pixel at coordinate d1,d2 which in the lab ref has coordinate:  $X1 = p1 \cdot \cos(\text{rot2}) \cdot \cos(\text{rot3}) + p2 \cdot (\cos(\text{rot3}) \cdot \sin(\text{rot1}) \cdot \sin(\text{rot2}) - \cos(\text{rot1}) \cdot \sin(\text{rot3})) - L \cdot (\cos(\text{rot1}) \cdot \cos(\text{rot3}) \cdot \sin(\text{rot2}) + \sin(\text{rot1}) \cdot \sin(\text{rot3}))$   $X2 = p1 \cdot \cos(\text{rot2}) \cdot \sin(\text{rot3}) - L \cdot (-\cos(\text{rot3}) \cdot \sin(\text{rot1})) + \cos(\text{rot1}) \cdot \sin(\text{rot2}) \cdot \sin(\text{rot3})) + p2 \cdot (\cos(\text{rot1}) \cdot \cos(\text{rot3}) + \sin(\text{rot1}) \cdot \sin(\text{rot2}) \cdot \sin(\text{rot3}))$   $X3 = -(L \cdot \cos(\text{rot1}) \cdot \cos(\text{rot2})) + p2 \cdot \cos(\text{rot2}) \cdot \sin(\text{rot1}) - p1 \cdot \sin(\text{rot2})$  hence  $\tan(\text{Chi}) = X2 / X1$

**Parameters**

**d1:** pixel coordinate along the 1st dimension (C convention)

(*type=float or array of them*)

**d2:** pixel coordinate along the 2nd dimension (C convention)

(*type=float or array of them*)

**path:** can be "tan" (i.e via numpy) or "cython"

**Return Value**

chi, the azimuthal angle in rad

**chi\_corner**(*self*, *d1*, *d2*)

Calculate the chi (azimuthal angle) for the corner of a pixel at coordinate d1,d2 which in the lab ref has coordinate:  $X1 = p1 \cdot \cos(\text{rot2}) \cdot \cos(\text{rot3}) + p2 \cdot (\cos(\text{rot3}) \cdot \sin(\text{rot1}) \cdot \sin(\text{rot2}) - \cos(\text{rot1}) \cdot \sin(\text{rot3})) - L \cdot (\cos(\text{rot1}) \cdot \cos(\text{rot3}) \cdot \sin(\text{rot2}) + \sin(\text{rot1}) \cdot \sin(\text{rot3}))$   $X2 = p1 \cdot \cos(\text{rot2}) \cdot \sin(\text{rot3}) - L \cdot (-\cos(\text{rot3}) \cdot \sin(\text{rot1})) + \cos(\text{rot1}) \cdot \sin(\text{rot2}) \cdot \sin(\text{rot3})) + p2 \cdot (\cos(\text{rot1}) \cdot \cos(\text{rot3}) + \sin(\text{rot1}) \cdot \sin(\text{rot2}) \cdot \sin(\text{rot3}))$   $X3 = -(L \cdot \cos(\text{rot1}) \cdot \cos(\text{rot2})) + p2 \cdot \cos(\text{rot2}) \cdot \sin(\text{rot1}) - p1 \cdot \sin(\text{rot2})$  hence  $\tan(\text{Chi}) = X2 / X1$

**Parameters**

d1: pixel coordinate along the 1st dimation (C convention)

(*type=float or array of them*)

d2: pixel coordinate along the 2nd dimation (C convention)

(*type=float or array of them*)

**Return Value**

chi, the azimuthal angle in rad

**chiArray**(*self*, *shape*)

Generate an array of the given shape with chi(i,j) (azimuthal angle) for all elements.

**cornerArray**(*self*, *shape*)

Generate a 3D array of the given shape with (i,j) (azimuthal angle) for all elements.

**cornerQArray**(*self*, *shape*)

Generate a 3D array of the given shape with (i,j) (azimuthal angle) for all elements.

**delta2Theta**(*self*, *shape*)

Generate a 3D array of the given shape with (i,j) with the max distance between the center and any corner in 2 theta

**deltaChi**(*self*, *shape*)

Generate a 3D array of the given shape with (i,j) with the max distance between the center and any corner in chi-angle

**deltaQ**(*self*, *shape*)

Generate a 3D array of the given shape with (i,j) with the max distance between the center and any corner in q\_vector

**diffSolidAngle**(*self*, *d1*, *d2*)

calculate the solid angle of the current pixels

**solidAngleArray**(*self*, *shape*)

Generate an array of the given shape with the solid angle of the current element two-theta(i,j) for all elements.

**save**(*self*, *filename*)

Save the refined parameters.

**Parameters**

**filename**: name of the file where to save the parameters  
(*type=string*)

**write**(*self*, *filename*)

Save the refined parameters.

**Parameters**

**filename**: name of the file where to save the parameters  
(*type=string*)

**sload**(*cls*, *filename*)

A static method combining the constructor and the loader from a

**Parameters**

**filename**: name of the file to load  
(*type=string*)

**Return Value**

instance of Geometry of AzimuthalIntegrator set-up with the parameter from the file.

**load**(*self*, *filename*)

Load the refined parameters from a file.

**Parameters**

**filename:** name of the file to load  
(*type=string*)

**read**(*self*, *filename*)

Load the refined parameters from a file.

**Parameters**

**filename:** name of the file to load  
(*type=string*)

**getPyFAI**(*self*)

return the parameter set from the PyFAI geometry as a dictionary

**setPyFAI**(*self*, **\*\*kwargs**)

set the geometry from a pyFAI-like dict

**getFit2D**(*self*)

return a dict with parameters compatible with fit2D geometry

---

**setFit2D**(*self*, *directDist*, *centerX*, *centerY*, *tilt*=0.0, *tiltPlanRotation*=0.0, *pixelX*=None, *pixelY*=None, *splineFile*=None)

---

Set the Fit2D-like parameter set: For geometry description see HPR 1996 (14) pp-240

**Parameters**

**direct:** direct distance from sample to detector along the incident beam (in millimeter as in fit2d)

**tilt:** tilt in degrees

**tiltPlanRotation:** Rotation (in degrees) of the tilt plan around the Z-detector axis \* 0deg -> Y does not move, +X goes to Z<0 \* 90deg -> X does not move, +Y goes to Z<0 \* 180deg -> Y does not move, +X goes to Z>0 \* 270deg -> X does not move, +Y goes to Z>0

**pixelX, pixelY:** as in fit2d they are given in micron, not in meter

**centerX, centerY:** pixel position of the beam center

**splineFile:** name of the file containing the spline

---

**setChiDiscAtZero**(*self*)

---

Set the position of the discontinuity of the chi axis between 0 and 2pi. By default it is between pi and -pi

---

**setChiDiscAtPi**(*self*)

---

Set the position of the discontinuity of the chi axis between -pi and +pi. This is the default behaviour

---

**setOversampling**(*self*, *iOversampling*)

---

set the oversampling factor

---

**oversampleArray**(*self*, *myarray*)

---



---

**polarization**(*self*, *shape*=None, *factor*=0.98)

---

Calculate the polarization correction according to the polarization factor:

**Parameters**

**factor:**  $(I_h - I_v) / (I_h + I_v)$ : varies between 0 (no polarization) and 1 (where division by 0 could occur) @return 2D array with polarization correction array (intensity/polarisation)

**reset**(*self*)

reset most arrays that are cached: used when a parameter changes.

**calcfrom1d**(*self*, *tth*, *I*, *shape=None*, *mask=None*, *dim1\_unit='2th\_deg'*, *correctSolidAngle=True*)

Computes a 2D image from a 1D integrated profile

**Parameters**

**tth**: 1D array with 2theta in degrees

**I**: scattering intensity @return 2D image reconstructed

**set\_dist**(*self*, *value*)

**get\_dist**(*self*)

**set\_poni1**(*self*, *value*)

**get\_poni1**(*self*)

**set\_poni2**(*self*, *value*)

**get\_poni2**(*self*)

**set\_rot1**(*self*, *value*)

**get\_rot1**(*self*)

**set\_rot2**(*self*, *value*)

**get\_rot2**(*self*)

**set\_rot3**(*self*, *value*)

**get\_rot3**(*self*)

**set\_wavelength**(*self*, *value*)

**get\_wavelength**(*self*)

`get_ttha(self)``set_ttha(self, value)``del_ttha(self)``get_chia(self)``set_chia(self, value)``del_chia(self)``get_dssa(self)``set_dssa(self, value)``del_dssa(self)``get_qa(self)``set_qa(self, value)``del_qa(self)``get_pixel1(self)``set_pixel1(self, pixel1)``get_pixel2(self)``set_pixel2(self, pixel2)``get_splineFile(self)``set_splineFile(self, splineFile)``get_spline(self)``set_spline(self, spline)`

```
get_correct_solid_angle_for_spline(self)
```

```
set_correct_solid_angle_for_spline(self, value)
```

### *Inherited from object*

```
__delattr__(), __format__(), __getattr__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(),  
__setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 7.2.2 Properties

Name	Description
dist	
poni1	
poni2	
rot1	
rot2	
rot3	
wavelength	
ttha	2theta array in cache
chia	chi array in cache
dssa	solid angle array in cache
qa	Q array in cache
pixel1	
pixel2	
splineFile	
spline	
correct_SA_spline	
<i>Inherited from object</i>	
__class__	

## 8 Module `pyFAI.geometryRefinement`

**Date:** 23/12/2011

**Author:** Jerome Kieffer

**Contact:** Jerome.Kieffer@ESRF.eu

**Copyright:** European Synchrotron Radiation Facility, Grenoble, France

**License:** GPLv3+

### 8.1 Variables

Name	Description
<code>__status__</code>	<b>Value:</b> 'development'
<code>logger</code>	<b>Value:</b> <code>logging.getLogger("pyFAI.geometryRefinement")</code>
<code>ROCA</code>	<b>Value:</b> '/opt/saxs/roca'
<code>__package__</code>	<b>Value:</b> 'pyFAI'

### 8.2 Class `GeometryRefinement`

object └

`pyFAI.geometry.Geometry` └

`pyFAI.azimuthalIntegrator.AzimuthalIntegrator` └ `pyFAI.geometryRefinement.GeometryRefinement`

## 8.2.1 Methods

---

```
__init__(self, data, dist=1, poni1=None, poni2=None, rot1=0, rot2=0,
rot3=0, pixel1=None, pixel2=None, splineFile=None, detector=None)
```

---

`x.__init__(...)` initializes x; see `x.__class__.__doc__` for signature

**Parameters**

**data:** ndarray float64 shape = n, 3 col0: pos in dim0 (in pixels)  
col1: pos in dim1 (in pixels) col2: associated tth value  
(in rad)

**detector:** name of the detector or Detector instance.

Overrides: `object.__init__`

---

```
guess_poni(self)
```

---

Poni can be guessed by the centroid of the ring with lowest 2Theta

---

```
set_tolerance(self, value=10)
```

---

**Parameters**

**value:** Tolerance as a percentage

---

```
residu1(self, param, d1, d2, tthRef)
```

---



---

```
residu2(self, param, d1, d2, tthRef)
```

---



---

```
refine1(self)
```

---



---

```
refine2(self, maxiter=1000000)
```

---



---

```
simplex(self, maxiter=1000000)
```

---



---

```
anneal(self, maxiter=1000000)
```

---



---

```
chi2(self, param=None)
```

---



---

```
roca(self)
```

---

run roca to optimise the parameter set

---

```
set_dist_max(self, value)
```

---

```
get_dist_max(self)
```

```
set_dist_min(self, value)
```

```
get_dist_min(self)
```

```
set_poni1_min(self, value)
```

```
get_poni1_min(self)
```

```
set_poni1_max(self, value)
```

```
get_poni1_max(self)
```

```
set_poni2_min(self, value)
```

```
get_poni2_min(self)
```

```
set_poni2_max(self, value)
```

```
get_poni2_max(self)
```

```
set_rot1_min(self, value)
```

```
get_rot1_min(self)
```

```
set_rot1_max(self, value)
```

```
get_rot1_max(self)
```

```
set_rot2_min(self, value)
```

```
get_rot2_min(self)
```

```
set_rot2_max(self, value)
```

```
get_rot2_max(self)
```

```
set_rot3_min(self, value)
```

get\_rot3\_min(*self*)

set\_rot3\_max(*self*, *value*)

get\_rot3\_max(*self*)

***Inherited from pyFAI.azimuthalIntegrator.AzimuthalIntegrator(Section 3.2)***

get\_darkcurrent(), get\_flatfield(), get\_mask(), get\_maskfile(), makeHeaders(), makeMask(), reset(), save1D(), save2D(), saxs(), set\_darkcurrent(), set\_flatfield(), set\_mask(), set\_maskfile(), setup\_LUT(), xrpd(), xrpd2(), xrpd2\_histogram(), xrpd2\_numpy(), xrpd2\_splitBBox(), xrpd2\_splitPixel(), xrpd\_LUT(), xrpd\_LUT\_OCL(), xrpd\_OpenCL(), xrpd\_cython(), xrpd\_numpy(), xrpd\_splitBBox(), xrpd\_splitPixel()

***Inherited from pyFAI.geometry.Geometry(Section 7.2)***

\_\_repr\_\_(), calcfrom1d(), chi(), chiArray(), chi\_corner(), cornerArray(), cornerQArray(), del\_chia(), del\_dssa(), del\_qa(), del\_ttha(), delta2Theta(), deltaChi(), deltaQ(), diffSolidAngle(), getFit2D(), getPyFAI(), get\_chia(), get\_correct\_solid\_angle\_for\_spline(), get\_dist(), get\_dssa(), get\_pixel1(), get\_pixel2(), get\_poni1(), get\_poni2(), get\_qa(), get\_rot1(), get\_rot2(), get\_rot3(), get\_spline(), get\_splineFile(), get\_ttha(), get\_wavelength(), load(), oversampleArray(), polarization(), qArray(), qCornerFunct(), qFunction(), read(), save(), setChiDiscAtPi(), setChiDiscAtZero(), setFit2D(), setOversampling(), setPyFAI(), set\_chia(), set\_correct\_solid\_angle\_for\_spline(), set\_dist(), set\_dssa(), set\_pixel1(), set\_pixel2(), set\_poni1(), set\_poni2(), set\_qa(), set\_rot1(), set\_rot2(), set\_rot3(), set\_spline(), set\_splineFile(), set\_ttha(), set\_wavelength(), sload(), solidAngleArray(), tth(), tth\_corner(), twoThetaArray(), write()

***Inherited from object***

\_\_delattr\_\_(), \_\_format\_\_(), \_\_getattr\_\_(), \_\_hash\_\_(), \_\_new\_\_(), \_\_reduce\_\_(), \_\_reduce\_ex\_\_(), \_\_setattr\_\_(), \_\_sizeof\_\_(), \_\_str\_\_(), \_\_subclasshook\_\_()

## 8.2.2 Properties

Name	Description
dist_max	
dist_min	
poni1_min	
poni1_max	
poni2_min	
poni2_max	
rot1_min	
rot1_max	
rot2_min	

*continued on next page*

Name	Description
rot2_max	
rot3_min	
rot3_max	
<i>Inherited from pyFAI.azimuthalIntegrator.AzimuthalIntegrator (Section 3.2)</i> darkcurrent, flatfield, mask, maskfile	
<i>Inherited from pyFAI.geometry.Geometry (Section 7.2)</i> chia, correct_SA_spline, dist, dssa, pixel1, pixel2, poni1, poni2, qa, rot1, rot2, rot3, spline, splineFile, ttha, wavelength	
<i>Inherited from object</i> __class__	

## 9 Module pyFAI.histogram

**Date:** 20120916

**Author:** Jerome Kieffer

### 9.1 Variables

Name	Description
<code>--package--</code>	<b>Value:</b> 'pyFAI'
<code>--test--</code>	<b>Value:</b> {}

## 10 Module pyFAI.ocl\_azim

C++ less implementation of Dimitris' code based on PyOpenCL

TODO and trick from dimitris still missing:

- \* dark-current subtraction is still missing
- \* In fact you might want to consider doing the conversion on the GPU when possible. Think about it, you have a uint16 to float which for large arrays was slow.. You load on the graphic card a uint16 (2x transfer speed) and you convert to float inside so it should be blazing fast.

**Date:** 07/11/2012

**Author:** Jerome Kieffer

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**License:** GPLv3

### 10.1 Variables

Name	Description
logger	<b>Value:</b> logging.getLogger("pyFAI.ocl_azim.pyocl")
--package--	<b>Value:</b> 'pyFAI'

### 10.2 Class Integrator1d

object └─ **pyFAI.ocl\_azim.Integrator1d**

Attempt to implements ocl\_azim using pyopencl

## 10.2.1 Methods

**`__init__(self, filename=None)`**

`x.__init__(...)` initializes `x`; see `x.__class__.__doc__` for signature

**Parameters**

**filename:** file in which profiling information are saved

Overrides: `object.__init__`

**`__dealloc__(self)`**

**`__repr__(self)`**

`repr(x)`

Overrides: `object.__repr__` extit(inherited documentation)

**`log(self, **kwarg)`**

log in a file all opencl events

**`getConfiguration(self, Nimage, Nbins, useFp64=None)`**

`getConfiguration` gets the description of the integrations to be performed and keeps an internal copy

**Parameters**

**Nimage:** number of pixel in image

**Nbins:** number of bins in regrouped histogram

**useFp64:** use double precision. By default the same as `init!`

**`configure(self, kernel=None)`**

The method `configure()` allocates the OpenCL resources required and compiled the OpenCL kernels. An active context must exist before a call to `configure()` and `getConfiguration()` must have been called at least once. Since the compiled OpenCL kernels carry some information on the integration parameters, a change to any of the parameters of `getConfiguration()` requires a subsequent call to `configure()` for them to take effect.

If a configuration exists and `configure()` is called, the configuration is cleaned up first to avoid OpenCL memory leaks

**Parameters**

**kernel\_path:** is the path to the actual kernel

---

**loadTth**(*self*, *tth*, *dtth*, *tth\_min*=None, *tth\_max*=None)

---

Load the 2th arrays along with the min and max value.

loadTth maybe be recalled at any time of the execution in order to update the 2th arrays.

loadTth is required and must be called at least once after a configure()

---

**setSolidAngle**(*self*, *solidAngle*)

---

Enables SolidAngle correction and uploads the suitable array to the OpenCL device.

By default the program will assume no solidangle correction unless setSolidAngle() is called. From then on, all integrations will be corrected via the SolidAngle array.

If the SolidAngle array needs to be changes, one may just call setSolidAngle() again with that array

**Parameters**

**solidAngle:** numpy array representing the solid angle of the given pixel

---

**unsetSolidAngle**(*self*)

---

Instructs the program to not perform solidangle correction from now on.

SolidAngle correction may be turned back on at any point

---

**setMask**(*self*, *mask*)

---

Enables the use of a Mask during integration. The Mask can be updated by recalling setMask at any point.

The Mask must be a PyFAI Mask. Pixels with 0 are masked out. TODO: check and invert!

**Parameters**

**mask:** numpy.ndarray of integer.

---

**unsetMask**(*self*)

---

Disables the use of a Mask from that point. It may be re-enabled at any point via setMask

**setDummyValue**(*self*, *dummy*, *delta\_dummy*)

Enables dummy value functionality and uploads the value to the OpenCL device.

Image values that are similar to the dummy value are set to 0.

**Parameters**

**dummy:** value in image of missing values (masked pixels?)

**delta\_dummy:** precision for dummy values

**unsetDummyValue**(*self*)

Disable a dummy value. May be re-enabled at any time by setDummyValue

**setRange**(*self*, *lowerBound*, *upperBound*)

Instructs the program to use a user - defined range for 2th values

setRange is optional. By default the integration will use the tth\_min and tth\_max given by loadTth() as integration range. When setRange is called it sets a new integration range without affecting the 2th array. All values outside that range will then be discarded when interpolating. Currently, if the interval of 2th ( $2th + -d2th$ ) is not all inside the range specified, it is discarded. The bins of the histogram are RESCALED to the defined range and not the original tth\_max - tth\_min range.

setRange can be called at any point and as many times required after a valid configuration is created.

**Parameters**

**lowerBound:** A float value for the lower bound of the integration range

**upperBound:** A float value for the upper bound of the integration range

**unsetRange**(*self*)

Disable the use of a user-defined 2th range and revert to tth\_min,tth\_max range

unsetRange instructs the program to revert to its default integration range. If the method is called when no user-defined range had been previously specified, no action will be performed

---

**execute**(*self*, *image*)

---

Perform a 1D azimuthal integration

execute() may be called only after an OpenCL device is configured and a Tth array has been loaded (at least once) It takes the input image and based on the configuration provided earlier it performs the 1D integration. Notice that if the provided image is bigger than N then only N points will be taken into account, while if the image is smaller than N the result may be catastrophic. set/unset and loadTth methods have a direct impact on the execute() method. All the rest of the methods will require at least a new configuration via configure().

Takes an image, integrate and return the histogram and weights

#### Parameters

**image:** image to be processed as a numpy array

#### Return Value

tth\_out, histogram, bins

TODO: to improve performances, the image should be casted to float32 in an optimal way: currently using numpy machinery but would be better if done in OpenCL

---

**init**(*self*, *devicetype*='GPU', *useFp64*=True, *platformid*=None, *deviceid*=None)

---

Initial configuration: Choose a device and initiate a context. Devicetypes can be GPU,gpu,CPU,cpu,DEF,ACC,ALL. Suggested are GPU,CPU. For each setting to work there must be such an OpenCL device and properly installed. E.g.: If Nvidia driver is installed, GPU will succeed but CPU will fail. The AMD SDK kit (AMD APP) is required for CPU via OpenCL.

#### Parameters

**devicetype:** string in ["cpu", "gpu", "all", "acc"]

**useFp64:** boolean specifying if double precision will be used

**platformid:** integer

**devid:** integer

**clean**(*self*, *preserve\_context=False*)

Free OpenCL related resources allocated by the library.

clean() is used to reinitiate the library back in a vanilla state. It may be asked to preserve the context created by init or completely clean up OpenCL.

Guard/Status flags that are set will be reset.

@param *preserve\_context* Flag that preserves the context (True) or destroys all OpenCL resources (False)

**get\_status**(*self*)

return a dictionnary with the status of the integrator: for compatibilty with former implementation

### *Inherited from object*

`__delattr__()`, `__format__()`, `__getattr__()`, `__hash__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`, `__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

### 10.2.2 Properties

Name	Description
<i>Inherited from object</i>	
<code>__class__</code>	

## 11 Module `pyFAI.ocl_azim_lut`

**Date:** 18/10/2012

**Author:** Jerome Kieffer

**Contact:** jerome.kieffer@esrf.fr

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**License:** GPLv3

### 11.1 Variables

Name	Description
<code>logger</code>	<b>Value:</b> <code>logging.getLogger("pyFAI.ocl_azim_lut")</code>
<code>__package__</code>	<b>Value:</b> <code>'pyFAI'</code>

### 11.2 Class `OCL_LUT_Integrator`

object └─ `pyFAI.ocl_azim_lut.OCL_LUT_Integrator`

#### 11.2.1 Methods

```
__init__(self, lut, image_size, devicetype='all', platformid=None,
deviceid=None, checksum=None)
```

`x.__init__(...)` initializes x; see `x.__class__.__doc__` for signature

#### Parameters

**lut:** array of uint32 - float32 with shape (nbins, lut\_size) with indexes and coefficients

**checksum:** pre - calculated checksum to prevent re - calculating it :)

Overrides: `object.__init__`

```
__del__(self)
```

Destructor: release all buffers

```
integrate(self, data, dummy=None, delta_dummy=None, dark=None,
flat=None, solidAngle=None, polarization=None, dark_checksum=None,
flat_checksum=None, solidAngle_checksum=None,
polarization_checksum=None)
```

### *Inherited from object*

```
__delattr__(), __format__(), __getattr__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(),
__repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 11.2.2 Properties

Name	Description
<i>Inherited from object</i>	
<code>__class__</code>	

## 12 Module pyFAI.opencl

**Date:** 06/11/2012

**Author:** Jerome Kieffer

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**License:** GPLv3+

### 12.1 Variables

Name	Description
<code>__status__</code>	<b>Value:</b> 'beta'
<code>logger</code>	<b>Value:</b> <code>logging.getLogger("pyFAI.opencl")</code>
<code>ocl</code>	<b>Value:</b> OpenCL devic...
<code>__package__</code>	<b>Value:</b> 'pyFAI'

### 12.2 Class Device

object └─  
          **pyFAI.opencl.Device**

Simple class that contains the structure of an OpenCL device

#### 12.2.1 Methods

```
__init__(self, name=None, type=None, version=None, driver_version=None,
          extensions='', memory=None, available=None, cores=None)
```

`x.__init__(...)` initializes x; see `x.__class__.__doc__` for signature

Overrides: `object.__init__` `exitit`(inherited documentation)

```
__repr__(self)
```

`repr(x)`

Overrides: `object.__repr__` `exitit`(inherited documentation)

*Inherited from object*

`__delattr__()`, `__format__()`, `__getattr__()`, `__hash__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`,  
`__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

### 12.2.2 Properties

Name	Description
<i>Inherited from object</i>	
<code>__class__</code>	

## 12.3 Class Platform

object └─ **pyFAI.openc1.Platform**

Simple class that contains the structure of an OpenCL platform

### 12.3.1 Methods

**`__init__(self, name=None, vendor=None, version=None, extensions=None)`**

`x.__init__(...)` initializes x; see `x.__class__.__doc__` for signature

Overrides: `object.__init__` extit(inherited documentation)

**`__repr__(self)`**

`repr(x)`

Overrides: `object.__repr__` extit(inherited documentation)

**`add_device(self, device)`**

### *Inherited from object*

`__delattr__()`, `__format__()`, `__getattr__()`, `__hash__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`,  
`__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

### 12.3.2 Properties

Name	Description
<i>Inherited from object</i>	

*continued on next page*

Name	Description
<code>--class--</code>	

## 12.4 Class *OpenCL*



Simple class that wraps the structure `ocl_tools.extended.h`

### 12.4.1 Methods

```

__repr__(self)
repr(x)
Overrides: object.__repr__ exitit(inherited documentation)

```

```

select_device(self, type='ALL', memory=None, extensions=[], best=True)

```

Select a device based on few parameters (at the end, keep the one with most memory)

#### Parameters

```

type:          "gpu" or "cpu" or "all" ....
memory:        minimum amount of memory (int)
extensions:    list of extensions to be present
best:          shall we look for the

```

```
create_context(self, devicetype='ALL', useFp64=False, platformid=None,
deviceid=None)
```

Choose a device and initiate a context.

Devicetypes can be GPU,gpu,CPU,cpu,DEF,ACC,ALL. Suggested are GPU,CPU. For each setting to work there must be such an OpenCL device and properly installed. E.g.: If Nvidia driver is installed, GPU will succeed but CPU will fail. The AMD SDK kit is required for CPU via OpenCL.

#### Parameters

**devicetype:** string in ["cpu","gpu", "all", "acc"]

**useFp64:** boolean specifying if double precision will be used

**platformid:** integer

**devid:** integer

#### Return Value

OpenCL context on the selected device

#### *Inherited from object*

`__delattr__()`, `__format__()`, `__getattr__()`, `__hash__()`, `__init__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`, `__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

#### 12.4.2 Properties

Name	Description
<i>Inherited from object</i>	
<code>__class__</code>	

#### 12.4.3 Class Variables

Name	Description
<code>platforms</code>	<b>Value:</b> [NVIDIA CUDA, AMD Accelerated Parallel Processing, Intel(...

## 13 Module pyFAI.peakPicker

**Date:** 23/12/2011

**Author:** J\xc3\xa9r\xc3\xebme Kieffer

**Contact:** Jerome.Kieffer@ESRF.eu

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**License:** GPLv3+

### 13.1 Variables

Name	Description
<code>__status__</code>	<b>Value:</b> 'development'
<code>logger</code>	<b>Value:</b> <code>logging.getLogger("pyFAI.peakPicker")</code>
<code>TARGET_SIZE</code>	<b>Value:</b> 1024
<code>__package__</code>	<b>Value:</b> 'pyFAI'

### 13.2 Class PeakPicker

object └─ `pyFAI.peakPicker.PeakPicker`

#### 13.2.1 Methods

<code>__init__(self, strFilename, reconst=False, mask=None)</code>
<code>x.__init__(...)</code> initializes x; see <code>x.__class__.__doc__</code> for signature
<b>Parameters</b>
<b>reconst:</b> shall negative values be reconstucted (wipe out problems with pilatus gaps)
Overrides: <code>object.__init__</code>
 <code>gui(self, log=False)</code>
<b>Parameters</b>
<b>log:</b> show z in log scale

<b>load</b> ( <i>self</i> , <i>filename</i> )
---

load a filename and plot data on the screen (if GUI)
--

<b>display_points</b> ( <i>self</i> )
---------------------------------------

<b>onclick</b> ( <i>self</i> , <i>event</i> )
---

<b>readFloatFromKeyboard</b> ( <i>self</i> , <i>text</i> , <i>dictVar</i> )
---

Read float from the keyboard ....
-----------------------------------

<b>Parameters</b>
-------------------

<b>text:</b> string to be displayed
-------------------------------------

<b>dictVar:</b> dict of this type: {1: [set_dist_min],3: [set_dist_min, set_dist_guess, set_dist_max]}
--

<b>finish</b> ( <i>self</i> , <i>filename</i> =None)
--

Ask the 2theta values for the given points
--

<b>contour</b> ( <i>self</i> , <i>data</i> )
--

<b>Parameters</b>
-------------------

<b>data:</b>
--------------

<b>massif_contour</b> ( <i>self</i> , <i>data</i> )
---

<b>Parameters</b>
-------------------

<b>data:</b>
--------------

<b>closeGUI</b> ( <i>self</i> )
---------------------------------

***Inherited from object***

`__delattr__()`, `__format__()`, `__getattr__()`, `__hash__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`, `__repr__()`, `__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

**13.2.2 Properties**

Name	Description
<i>Inherited from object</i>	
<code>__class__</code>	

### 13.3 Class *ControlPoints*

object └─  
**pyFAI.peakPicker.ControlPoints**

This class contains a set of control points with (optionaly) their diffrection 2Theta angle

#### 13.3.1 Methods

**`__init__(self, filename=None)`**

`x.__init__(...)` initializes `x`; see `x.__class__.__doc__` for signature

Overrides: `object.__init__` extit(inherited documentation)

**`__repr__(self)`**

`repr(x)`

Overrides: `object.__repr__` extit(inherited documentation)

**`__len__(self)`**

**`check(self)`**

check internal consistency of the class

**`reset(self)`**

remove all stored values and resets them to default

**`append(self, points, angle=None)`**

**Parameters**

`point`: list of points

`angle`: 2-theta angle in radians

**`append_2theta_deg(self, points, angle=None)`**

**Parameters**

`point`: list of points

`angle`: 2-theta angle in degrees

**pop**(*self*, *idx=None*)

Remove the set of points at given index (by default the last)

**Parameters**

**idx**: poistion of the point to remove

**save**(*self*, *filename*)

Save a set of control points to a file

**Parameters**

**filename**: name of the file

**Return Value**

None

**load**(*self*, *filename*)

load all control points from a file

**getList**(*self*)

Retrieve the list of control points suitable for geometry refinement

**readAngleFromKeyboard**(*self*)

Ask the 2theta values for the given points

**setWavelength**(*self*, *value=None*)

**getWavelength**(*self*)

**Inherited from object**

`__delattr__()`, `__format__()`, `__getattribute__()`, `__hash__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`, `__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

**13.3.2 Properties**

Name	Description
wavelength	
<i>Inherited from object</i>	
<code>__class__</code>	

## 13.4 Class Massif

object —  
**pyFAI.peakPicker.Massif**

A massif is defined as an area around a peak, it is used to find neighbouring peaks

### 13.4.1 Methods

**\_\_init\_\_**(*self*, *data*=None)

*x*.\_\_init\_\_(...) initializes *x*; see *x*.\_\_class\_\_.\_\_doc\_\_ for signature

Overrides: object.\_\_init\_\_

**nearest\_peak**(*self*, *x*)

@returns the coordinates of the nearest peak

**calculate\_massif**(*self*, *x*)

defines a map of the massif around *x* and returns the mask

**find\_peaks**(*self*, *x*, *nmax*=200, *annotate*=None, *massif\_contour*=None, *stdout*=sys.stdout)

All in one function that finds a maximum from the given seed (*x*) then calculates the region extension and extract position of the neighboring peaks.

#### Parameters

**x:** seed for the calculation, input coordinates  
**nmax:** maximum number of peak per region  
**annotate:** call back method taking number of points + coordinate as input.  
**massif\_contour:** callback to show the contour of a massif with the given index.  
**stdout:** this is the file where output is written by default.

#### Return Value

list of peaks

**initValleySize**(*self*)

**getValleySize**(*self*)

<code>setValleySize(<i>self</i>, <i>size</i>)</code>
--

<code>delValleySize(<i>self</i>)</code>
---

<code>getBinnedData(<i>self</i>)</code>
---

@return binned data
---------------------

<code>getMedianData(<i>self</i>)</code>
---

<code>getBluredData(<i>self</i>)</code>
---

<code>getLabeledMassif(<i>self</i>, <i>pattern</i>=None)</code>
---

### *Inherited from object*

`__delattr__()`, `__format__()`, `__getattr__()`, `__hash__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`,  
`__repr__()`, `__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

### 13.4.2 Properties

Name	Description
valley_size	Defines the minimum distance between two massifs
<i>Inherited from object</i>	
__class__	

## 14 Module `pyFAI.reconstruct`

### 14.1 Variables

Name	Description
<code>--package--</code>	<b>Value:</b> <code>'pyFAI'</code>
<code>--test--</code>	<b>Value:</b> <code>{}</code>

## 15 Module pyFAI.refinement2D

**Date:** 23/08/2012

**Author:** J\xc3\xa9r\xc3\xbbme Kieffer

**Contact:** Jerome.Kieffer@ESRF.eu

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**License:** GPLv3+

### 15.1 Variables

Name	Description
<code>__status__</code>	<b>Value:</b> 'beta'
<code>logger</code>	<b>Value:</b> <code>logging.getLogger("pyFAI.refinement2D")</code>
<code>__package__</code>	<b>Value:</b> 'pyFAI'

### 15.2 Class Refinement2D

object └─ **pyFAI.refinement2D.Refinement2D**

refine the parameters from image itself ...

#### 15.2.1 Methods

```
__init__(self, img, ai=None)
```

x.\_\_init\_\_(...) initializes x; see x.\_\_class\_\_.\_\_doc\_\_ for signature

Overrides: object.\_\_init\_\_

```
get_shape(self)
```

<b>reconstruct</b> ( <i>self</i> , <i>tth</i> , <i>I</i> )
--

Reconstruct a perfect image according to 2th / I given in input
---

<b>Parameters</b>
-------------------

<b>tth</b> : 2 theta array
----------------------------

<b>I</b> : intensity array
----------------------------

<b>diff_tth_X</b> ( <i>self</i> , <i>dx</i> =0.1)
---

<b>diff_tth_tilt</b> ( <i>self</i> , <i>dx</i> =0.1)
--

<b>diff_Fit2D</b> ( <i>self</i> , <i>axis</i> ='all', <i>dx</i> =0.1)
---

<b>scan_centerX</b> ( <i>self</i> , <i>width</i> =1.0, <i>points</i> =10)
---

<b>scan_tilt</b> ( <i>self</i> , <i>width</i> =1.0, <i>points</i> =10)
--

<b>scan_Fit2D</b> ( <i>self</i> , <i>width</i> =1.0, <i>points</i> =10, <i>axis</i> ='tilt', <i>dx</i> =0.1)
--

***Inherited from object***

`__delattr__()`, `__format__()`, `__getattr__()`, `__hash__()`, `__new__()`, `__reduce__()`, `__reduce_ex__()`,  
`__repr__()`, `__setattr__()`, `__sizeof__()`, `__str__()`, `__subclasshook__()`

### 15.2.2 Properties

Name	Description
shape	
<i>Inherited from object</i>	
__class__	

## 16 Module pyFAI.relabel

**Date:** 20120916

**Author:** Jerome Kieffer

**Contact:** Jerome.kieffer@esrf.fr

**License:** GPLv3+

### 16.1 Variables

Name	Description
<code>--package--</code>	<b>Value:</b> 'pyFAI'
<code>--status--</code>	<b>Value:</b> 'stable'
<code>--test--</code>	<b>Value:</b> {}

## 17 Module pyFAI.spline

This piece of software aims to manipulate spline files for geometric corrections of the 2D detectors using cubic-spline

**Author:** Jérôme Kieffer

**Contact:** Jerome.Kieffer@esrf.eu

**Copyright:** European Synchrotron Radiation Facility, Grenoble, France

**License:** GPLv3+

### 17.1 Variables

Name	Description
<code>__package__</code>	<b>Value:</b> 'pyFAI'

### 17.2 Class Spline

This class is a python representation of the spline file. Those files represent cubic splines for 2D detector distortions and make heavy use of fitpack (dierckx in netlib) — A Python-C wrapper to FITPACK (by P. Dierckx). FITPACK is a collection of FORTRAN programs for curve and surface fitting with splines and tensor product splines. See <http://www.cs.kuleuven.ac.be/cwis/research> or <http://www.netlib.org/dierckx/index.html>

#### 17.2.1 Methods

<code>__init__(self, filename=None)</code>
--

this is the constructor of the Spline class, for
--

<code>__repr__(self)</code>
-----------------------------

---

**zeros**(*self*, *xmin*=0.0, *ymin*=0.0, *xmax*=2048.0, *ymax*=2048.0, *pixSize*=None)

---

defines a spline file with no ( zero ) displacement.

**Parameters**

**xmin**: minimum coordinate in x, usually zero  
(*type=float*)

**xmax**: maximum coordinate in x (+1) usually 2048  
(*type=float*)

**ymin**: minimum coordinate in y, usually zero  
(*type=float*)

**ymax**: maximum coordinate y (+1) usually 2048  
(*type=float*)

---

**zeros\_like**(*self*, *other*)

---

defines a spline file with no ( zero ) displacement with the same shape as the other one given.

**Parameters**

**other**: another Spline  
(*type=Spline*)

---

**read**(*self*, *filename*)

---

read an ascii spline file from file

**Parameters**

**filename**: name of the file containing the cubic spline distortion file  
(*type=string*)

---

**comparison**(*self*, *ref*, *verbose*=False)

---

Compares the current spline distortion with a reference

**Parameters**

**ref**: another spline file

**Return Value**

True or False depending if the splines are the same or not

**spline2array**(*self*, *timing=False*)

calculates the displacement matrix using fitpack bisplev(x, y, tck, dx = 0, dy = 0)

Evaluate a bivariate B-spline and its derivatives. Return a rank-2 array of spline function values (or spline derivative values) at points given by the cross-product of the rank-1 arrays x and y. In special cases, return an array or just a float if either x or y or both are floats.

**splineFuncX**(*self*, *x*, *y*)

calculates the displacement matrix using fitpack for the X direction

**Parameters**

**x**: numpy array representing the points in the x direction

**y**: numpy array representing the points in the y direction

**Return Value**

displacement matrix for the X direction

(*type=numpy arrays*)

**splineFuncY**(*self*, *x*, *y*)

calculates the displacement matrix using fitpack for the Y direction

**Parameters**

**x**: numpy array representing the points in the x direction

**y**: numpy array representing the points in the y direction

**Return Value**

displacement matrix for the Y direction

(*type=numpy array*)

**array2spline**(*self*, *smoothing=1000*, *timing=False*)

calculates the spline coefficients from the displacements matrix using fitpack

**writeEDF**(*self*, *basename*)

save the distortion matrices into a couple of files called basename-x.edf and basename-y.edf

---

**write**(*self*, *filename*)

---

save the cubic spline in an ascii file usable with Fit2D or SPD

**Parameters**

**filename:** name of the file containing the cubic spline distortion file  
(*type=string*)

---



---

**tilt**(*self*, *center*=(0.0, 0.0), *tiltAngle*=0.0, *tiltPlanRot*=0.0, *distanceSampleDetector*=1.0, *timing*=False)

---

The tilt method apply a virtual tilt on the detector, the point of tilt is given by the center

**Parameters**

**center:** position of the point of tilt, this point will not be moved.  
(*type=2tuple of floats*)

**tiltAngle:** the value of the tilt in degrees  
(*type=float in the range [-90:+90] degrees*)

**tiltPlanRot:** the rotation of the tilt plan with the Ox axis (0 deg for y axis invariant, 90 deg for x axis invariant)  
(*type=Float in the range [-180:180]*)

**distanceSampleDetector:** the distance from sample to detector in meter (along the beam, so distance from sample to center)  
(*type=float*)

---

**Return Value**

tilted Spline instance  
(*type=Spline*)

---



---

**setPixelSize**(*self*, *pixelSize*)

---

sets the size of the pixel from a 2-tuple of floats expressed in meters.

**Parameters**

**pixelSize:** (*type=2-tuple of float*)

---

**getPixelSize**(*self*)**Return Value**

the size of the pixel from a 2D detector

*(type=2-tuple of floats expressed in meter.)***bin**(*self*, *binning*=None)

## 18 Module `pyFAI.splitBBox`

### 18.1 Variables

Name	Description
<code>--package--</code>	<b>Value:</b> <code>'pyFAI'</code>
<code>--test--</code>	<b>Value:</b> <code>{}</code>

## 19 Module `pyFAI.splitBBoxLUT`

### 19.1 Variables

Name	Description
<code>--package--</code>	<b>Value:</b> <code>'pyFAI'</code>
<code>--test--</code>	<b>Value:</b> <code>{}</code>

## 20 Module pyFAI.splitPixel

### 20.1 Variables

Name	Description
<code>--package--</code>	<b>Value:</b> 'pyFAI'
<code>--test--</code>	<b>Value:</b> {}

## 21 Module pyFAI.utils

### 21.1 Functions

**timeit**(*func*)

**gaussian\_filter**(*input*, *sigma*, *mode*='reflect', *cval*=0.0)

2-dimensional Gaussian filter implemented with FFTw

**Parameters**

**input**: input array to filter  
(*type=array-like*)

**sigma**: standard deviation for Gaussian kernel. The standard deviations of the Gaussian filter are given for each axis as a sequence, or as a single number, in which case it is equal for all axes.  
(*type=scalar or sequence of scalars*)

**mode**: {'reflect', 'constant', 'nearest', 'mirror', 'wrap'}, optional The “mode” parameter determines how the array borders are handled, where “cval” is the value when mode is equal to 'constant'. Default is 'reflect'

**cval**: scalar, optional Value to fill past edges of input if “mode” is 'constant'. Default is 0.0

**expand**(*input*, *sigma*, *mode*='constant', *cval*=0.0)

Expand array a with its reflection on boundaries

**Parameters**

**a**: 2D array

**sigma**: float or 2-tuple of floats

**mode**: "constant", "nearest" or "reflect"

**cval**: filling value used for constant, 0.0 by default

---

**relabel**(*label, data, blurred, max\_size=None*)

Relabel limits the number of region in the label array. They are ranked relatively to their max(I0)-max(blur(I0))

**Parameters**

**label:** a label array coming out of  
scipy.ndimage.measurement.label

**data:** an array containing the raw data

**blurred:** an array containing the blurred data

**max\_size:** the max number of label wanted @return array like label

---

**averageImages**(*listImages, output=None, threshold=0.1, minimum=None, maximum=None, darks=None, flats=None*)

Takes a list of filenames and create an average frame discarding all saturated pixels.

**Parameters**

**listImages:** list of string representing the filenames

**output:** name of the optional output file

**threshold:** what is the upper limit? all pixel > max\*(1-threshold) are discarded.

**minimum:** minimum valid value or True

**maximum:** maximum valid value

**darks:** list of dark current images for subtraction

**flats:** list of flat field images for division

---

**boundingBox**(*img*)

Tries to guess the bounding box around a valid massif

**Parameters**

**img:** 2D array like

**Return Value**

4-tuple (d0\_min, d1\_min, d0\_max, d1\_max)

**removeSaturatedPixel**(*ds*, *threshold*=0.1, *minimum*=None, *maximum*=None)

#### Parameters

**ds**: a dataset as ndarray  
**threshold**: what is the upper limit? all pixel > max\*(1-threshold) are discarded.  
**minimum**: minimum valid value (or True for auto-guess)  
**maximum**: maximum valid value

#### Return Value

another dataset

**binning**(*inputArray*, *binsize*)

#### Parameters

**inputArray**: input ndarray  
**binsize**: int or 2-tuple representing the size of the binning

#### Return Value

binned input ndarray

**unBinning**(*binnedArray*, *binsize*)

#### Parameters

**binnedArray**: input ndarray  
**binsize**: 2-tuple representing the size of the binning

#### Return Value

unBinned input ndarray

## 21.2 Variables

Name	Description
logger	<b>Value:</b> logging.getLogger("pyFAI.utils")
timelog	<b>Value:</b> logging.getLogger("pyFAI.timeit")
__package__	<b>Value:</b> 'pyFAI'

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